Fiber Transport in the Respiratory Airways

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Background

- Health risks associated nanoparticles
- Exposure by inhalation
- Implications of particle shape
- Asbestos fibers and nanotubes
- Transport and deposition properties

Fiber Modeling

- Translational and rotational motion
- Spheres with equivalent diameters vs. fiber orientation
- Fiber Stokes number $<< 1 \rightarrow$ neglect inertia
- Ellipsoid of revolution.
- Fiber aspect ratio, $\beta = c/b$



Coordinate frames

- Two coordinate systems
 - global (x,y,z), fixed in space
 - local (x',y',z'), fixed to fiber
- Rotation matrix A transforms from local to global coordinates

 $\mathbf{x'} = A\mathbf{x}$

Fiber orientation & rotation matrix

Euler angles

 $A = \begin{bmatrix} \cos\psi \cos\phi - \cos\theta \sin\phi \sin\phi & \cos\psi \sin\phi + \cos\theta \cos\phi \sin\psi & \sin\theta \sin\psi \\ -\sin\psi \cos\phi - \cos\theta \sin\phi \cos\psi & \cos\theta \cos\phi \cos\psi - \sin\psi \sin\phi & \sin\theta \cos\psi \\ & \sin\theta \sin\phi & -\sin\theta \cos\phi & \cos\theta \end{bmatrix}$



Quaternions

$$A = 2 \begin{pmatrix} q_1^2 + q_4^2 - \frac{1}{2} & q_1q_2 + q_3q_4 & q_1q_3 - q_2q_4 \\ q_1q_2 - q_3q_4 & q_2^2 + q_4^2 - \frac{1}{2} & q_2q_3 + q_1q_4 \\ q_1q_3 + q_2q_4 & q_2q_3 - q_1q_4 & q_3^2 + q_4^2 - \frac{1}{2} \end{pmatrix}$$

$$q_{1} = \sin\frac{\theta}{2}\cos\frac{\phi - \psi}{2}, \qquad q_{3} = \cos\frac{\theta}{2}\sin\frac{\phi + \psi}{2},$$
$$q_{2} = \sin\frac{\theta}{2}\sin\frac{\phi - \psi}{2}, \qquad q_{4} = \cos\frac{\theta}{2}\cos\frac{\phi + \psi}{2},$$
$$\sum_{n} q_{n}^{2} = 1$$

Euler angles

+ Intuitive

 Singular terms for certain angles → not suited for rigid motion simulations for fibers undergoing full rotations.

Quaternions

Abstract

+ Well-behaved equations of motion

+ No trigonometric functions in rotation matrix

+ Numerical drift easily controlled

Equations for fiber translation

$$F_{grav,i} + F_{drag,i} + F_{Br,i} = 0$$

$$F_{grav} = \frac{\pi \rho_f g d_f^3 \beta}{6} \quad \text{in z-dir}$$
$$F_{drag,i} = 3\pi \mu d_{i'} \left(u_i - \frac{dx_i}{dt} \right)$$

$$\frac{d_{\rm o}}{d_{\rm f}} = \frac{\frac{4}{3}(\beta^2 - 1)}{C_{\rm o}\left[\frac{2\beta^2 - 1}{\sqrt{\beta^2 - 1}}\ln(\beta + \sqrt{\beta^2 - 1}) - \beta\right]},$$

$$\frac{d_{\perp}}{d_f} = \frac{\frac{8}{3}(\beta^2 - 1)}{C_{\perp}\left[\frac{2\beta^2 - 3}{\sqrt{\beta^2 - 1}}\ln(\beta + \sqrt{\beta^2 - 1}) + \beta\right]}.$$

Fiber equation of motion

Non-dimensional variables:

 $x^* = x/R, t^* = tU/R, u^* = u/U$

$$\begin{bmatrix} \frac{dx^{*}}{dt^{*}} \\ \frac{dy^{*}}{dt^{*}} \\ \frac{dz^{*}}{dt^{*}} \end{bmatrix} = \begin{bmatrix} u^{*} \\ v^{*} \\ W^{*} \end{bmatrix} + A^{T} \begin{bmatrix} \frac{d_{f}}{d_{\perp}} & 0 & 0 \\ 0 & \frac{d_{f}}{d_{\perp}} & 0 \\ 0 & 0 & \frac{d_{f}}{d_{\parallel}} \end{bmatrix} A \begin{bmatrix} 0 \\ 0 \\ k \end{bmatrix} + A^{T} \begin{bmatrix} f_{Br,x^{'}}(t^{*}) \\ f_{Br,y^{'}}(t^{*}) \\ f_{Br,z^{'}}(t^{*}) \end{bmatrix}, \qquad k = \frac{\rho_{f}gd_{f}^{2}\beta}{18\mu U}$$
Local coordinates
Local coordinates

Components of fiber velocity

$$\frac{dx^{*}}{dt^{*}} = u^{*} + 4k \left[\left(\frac{d_{f}}{d_{\Box}} - \frac{d_{f}}{d_{\bot}} \right) (q_{1}q_{3} + q_{2}q_{4}) \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,x'} \left(q_{1}^{2} + q_{4}^{2} - \frac{1}{2} \right) + f^{*}_{Br,y'} \left(q_{1}q_{2} - q_{3}q_{4} \right) \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,x'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(q_{1}q_{3} + q_{2}q_{4} \right) \right] + 2 \left[f^{*}_{Br,$$

$$\frac{dy^{*}}{dt^{*}} = v^{*} - 4k \left[\left(\frac{d_{f}}{d_{\Box}} - \frac{d_{f}}{d_{\bot}} \right) (q_{1}q_{4} - q_{2}q_{3}) \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,x'} (q_{1}q_{2} + q_{3}q_{4}) + f^{*}_{Br,y'} (q_{2}^{2} + q_{4}^{2} - \frac{1}{2}) + f^{*}_{Br,z'} (q_{2}q_{3} - q_{1}q_{4}) \right]$$

$$\frac{dz^{*}}{dt^{*}} = w^{*} + 4k \left[\frac{d_{f}}{d_{\Box}} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right)^{2} + \frac{d_{f}}{d_{\bot}} \left(q_{1}^{2} + q_{2}^{2} \right) \left(q_{3}^{2} + q_{4}^{2} \right) \right] + 2 \left[f^{*}_{Br,x'} \left(q_{1}q_{3} - q_{2}q_{4} \right) + f^{*}_{Br,y'} \left(q_{2}q_{3} + q_{1}q_{4} \right) \right] + 4k \left[\frac{d_{f}}{d_{\Box}} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right)^{2} + \frac{d_{f}}{d_{\bot}} \left(q_{1}^{2} + q_{2}^{2} \right) \left(q_{3}^{2} + q_{4}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{1}^{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z'} \left(\frac{1}{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z''} \left(\frac{1}{2} - q_{2}^{2} \right) \right] + 2 \left[f^{*}_{Br,z''} \left(\frac{$$

Solved using MATLAB



Results



Small drift motion





Microfibers





Nanofibers



Thank you

Questions?